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Designing and Implementing the Remote Control and Monitoring System for Industrial Automation

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Abstract— Abstract— This paper presents design and implementation of a human machine (HMI) programmable logic interface for a controller (PLC) based automated process that can be remotaely controlled and monitored using mobile application. moving products conveyor belt the to destined place for packaging, is controlled by **LOGO** 230 **RCE** Siemens PLC. Microcontroller operates the relays according to the output of IR sensors, which are used sense the products. States of relays taken as the input of the PLC. An HMI is designed with an android application and the microcontroller establish a communication path between the operators and PLC based plant. The interface provides remote controlling and monitoring feature. The proposed design minimized overall cost by replacing the widely used supervisory control and data (SCADA) acquisition system with normal sensors and mobile application based control. The performance of the implemented prototype evaluated through several real-time operations, it shows satisfactory results.

I. INTRODUCTION

Industrial automation is of one most global trends that enhances the quality of production, safety and proper utilization of plant and resources. From the economic view, mass production is the main goal of any industry to stay ahead in the recent competitive market [1]. The production often eased through the method automation. any kind of industry, packaging is a widely used process. Packaging is done for providing protection and safety of products

from dust, moistures and other objects that are harmful to the products. The packaging provides better handling, transporting also and, stable storage capability, company branding and many more [2]. The manual process toilsome work packaging is and costly, as a large number workers required for it. Therefore, many companies switching to industrial automation for costeffective uninterrupted production. and Automation of the packaging process monitoring system remote control and reliable provide more and developed packaging with less error and less probability of hazards [3]. industry, essential In an equipment product processing of conveyor belt. Conveyor belt performs functions include rotation, accumulation, flipping, stacking, and diversion of products depending upon the application. several conveyor belt systems used in are industries. In Table I, numerous belt systems are enlisted with their working domain [4].

TABLE I
CONVEYOR BELTS AND WORKING DOMAIN

Working Domain				
Belt, rings or chains powered rollers				
Diverts product one region to another or one belt to another. Mainly used for				
sorting.				
Holds products for a fixed time or for a fixed quantity gathering.				
Consist of helix pushes loose products forward such as powdered or mixed products.				
Conveyed products to upward.				

In the area of industrial automation, programmable logic controller (PLC) found

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greater interest for its robustness and low-cost implementation. PLC is a kind of small industrial computer specially designed for purpose, performs several functions including logical operations, counting and arithmetic functions control various to process machinery through digital or analog modules [5]. Various automation of packaging using PLC supervisory control and has been proposed and implemented by numerous researchers around the world. Each automation has its own pros and cons. A brief discussion has been made on the various automation of packaging processes in Section II. It is found that most of the automation is applicable for large industries, complex in nature, expensive and not affordable for small industries. the aforementioned limitations, overcome costly and simple affordable. lessprocess is proposed. The main contributions of this paper are:

- For i. lower capital industries, **SCADA** and other supervisory devices are for feedback and monitoring, used which are costly to implement. this paper, an HMI is implemented with low-cost equipment and easier accessing technology
- **Implemented** ii. a mobile-based user interface application i.e. an android that user-friendly easy is and operate and learn.
- iii. Developed a platform for improvising and innovation in mobile-based industrial automation with low cost, robustness, and reliability.

In this paper, a prototype of two conveyor considered, is one for products destined box and another carrying to the for carrying filled and unfilled boxes. PLC is designed as the controller for a constant speed geared DC which motor, rolls the conveyor belt. An interface is designed based on android platform, arduino uno and module to control monitor the packaging process. The novelty of the proposed system is that it has been found suitable and cost-effective for small industries where capital is small. This work can also be implemented for large industries considering the requirements of robustness and application field.

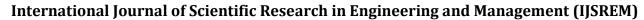
II.RELATED WORKS

In recent years, many works on automation and remote monitoring and control of packaging process have been done. Several papers are studied and the contribution have been enlisted, in Table II.

TABLE II
RELATED WORKS ON AUTOMATION OF PACKAGING PROCESS AND REMOTE CONTROL AND MONITORING

Author	Contribution
Marie M. Baroro, Joanna & Alipio et al. [6]	Implemented packaging and material handling using PLC and recommended an HMI for controlling purpose.
Abueejela, Yousef & A. Algitta et al. [7]	Implemented automatic packaging machine by controlling the conveyor belt using PLC.
P.Thirumurugan et al. [8]	Implemented metal separating and packaging machine using PLC and a metallic sensor for detecting metals and non-metals.
Gupta, T & Kamboj, S et al. [9]	Proposed a design of packaging process using PLC and SCADA for remote control and monitoring with a software interface to visualize the process. SCADA and PLC interconnection has been proposed for reprogramming the PLC. Developed and implemented a
Shyr, Wen-Jye, Te- Jen Su and Chia- Ming Lin et al. [10]	methodology for remote controlling and monitoring of plant using PLC. A web-server based computer system and Web-Cam are used to remote monitoring and connected computer through the internet can control the plant from the remote place.
J. Garcia et al. [11]	Using SCADA and TCP/IP developed a platform using Motronic software interface for real-time remote monitoring and controlling of the plant and configure new device to add with, re-configure the existed device.

Table II, It have be From seen that, powerful and more costly remote controlling supervisory systems and are proposed for industrial applications. However, for small industries or industries where hardiness is required, these not abovementioned proposed designs seems unnecessary. this, the purpose of this paper is to find alternate technology and reduce cost of automation. Moreover, an automation system





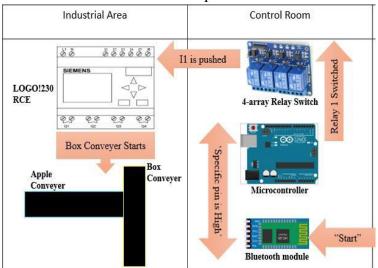
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has been designed which can be easily implemented for low cost industries and for large industries where only monitoring is required rather than robustness.

METHODOLOGY

A. Start Packaging System

Tapping the "Start" button on android application, a specific data (e.g. "a") mobile. Bluetooth module (HC-05)receives the transmitted data. which processed microcontroller (arduino by a uno). Arduino uno makes a particular pin as logical "High" for one second, which will control the switching of relay switch (four-array relay switch 5v DC). This will make arduino uno to send a link "packaging starts" through bluetooth module to the mobile. This relay switch provides logical information to the respective PLC input (e.g. I1). PLC module then operates logical operations to close or open respective output relay. Electrical dc motor can be used as an output actuator to move



box or sample conveyor belt, as shown in Fig. 1.

Fig. 1 Proposed procedure of start packaging system

B. Box Sensing and Counting

Box conveyor run until a box is sensed by the IR sensor. Sensing of a box arduino makes uno to make another logical "High" for one second and send sensed" string e.g., "1 another box is to mobile of phone including the number

boxes. That pin also controls the switching of a relay switch providing logical information to the respective PLC input (e.g. I4). PLC module stops the box conveyor belt and begins to move sample conveyor belt.

C. Sample Sensing and Counting

Samples (e.g. apple) on the running sample conveyor belt are passed before the sensors (mounted on the sample conveyor structure). IR sensors senses arduino uno process this signal to make a "High" logical for one second. Moreover, arduino send a string to mobile e.g., "1 sample is sensed" and a counter is started to count the sample. The "High" pin provides logical information to the respective PLC input (e.g. I3). **PLC** sample conveyor module stops the when three samples have been counted and begin to move box conveyor belt. In such a way, every box is filled with three samples.

D. Stop Packaging System

Box sensing, apple sensing, and counting will be continued until an interruption is command sent from the mobile application. When the "stop" or "exit" button is tapped on the mobile module application, the **PLC** stops the packaging system and initializes the number of boxes and samples.

II. SOFTWARE IMPLEMENTATION

Software implementation includes **PLC** diagram, implementation of ladder application developing an android and configuring necessary programs (remote control and monitoring system) for arduino.

A. PLC Ladder Diagram

For programming and operation of the presented prototype, a PLC ladder diagram is applied by using LOGO! Soft V8. For a uncomplicated and faster. space-saving solution, LOGO! is a perfect choice. LOGO! Comfort makes possible easier installation with a minimum wiring effort

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[14]. This ladder diagram, as shown in Fig. 2 provides two stages of the packaging operation. The input, output, relay switch and counter configuration are shown in Table III.

TABLE III
INPUT, OUTPUT AND RELAY CONFIGURATIONS OF PLC

Input				Ou	tput
I1	I2	I3	I4	Q1	Q2
PLC starts	PLC stops	Apple or sample sensed	Box sense d	Apple or sample conveyo r belt	Box conveyo r belt
Relays			Cou	inter	
M1 M2		C001			
Relay contacts		Relay contacts		Apple Counter	

1) Carrying Empty Boxes to Desired Location

Flag "make contact" M1 is connected with "make contact" I1 (packaging starts) to provide an OR gate operation. The output of the OR gate and "break contact" (packaging stops) provides an AND logic gate operation to operate flag output coil M1. and flag "break Flag "make contact" M1contact" M2provide an AND logic gate operation to operate relay output coil (box conveyor). Flag "make contact" M2 is connected with "make contact" I4 to provide OR gate operation. The output of the OR gate and "break contact" C001 provide an AND logic gate operation to operate flag output coil M2. Therefore, once packaging starts (I1 logically high), box conveyor (Q2 relay output coil energies) starts to move unless "packaging stops" (I2 logically high) command is applied or a box is detected (flag M2 is logically high).

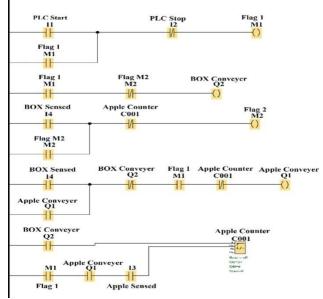
2) Packaging Samples into Boxes

output coil "make contact" connected with "make contact" and provides an OR gate operation. The output of OR gate, relay output coil "break

contact" Q2, flag "make contact" the and sample counter "break contact" AND logic gate provide an operation output coil operate relay Q1 (apple or sample conveyor). apple An or C001 is introduced. C001 counter reset if relay output coil Q2 (box conveyor) logically high. Flag make contact M1, relay output coil make contact Q1 (apple or conveyor) and "make contact" provide an AND logic gate operation to count the number of samples.

B. Developing an Android Application

Android-based PLC remote control and monitoring application is developed using



Android Studio (emulator) [15]. This application provides a single row display for wireless monitoring and three control buttons, as shown in Fig. 3.

Fig. 2 Ladder diagram of the automatic packaging system.

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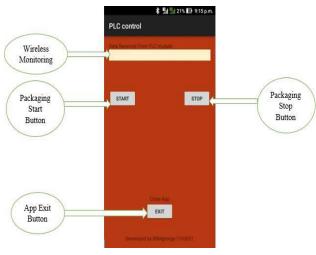


Fig. 3 An android application of automatic packaging & monitoring system.

C. Configuring Remote Control and Monitoring Programs to Arduino

Arduino, open-source electronics an prototyping platform that is based flexible, easy-to-use hardware and software. Arduino is a tiny computer system can be programmed with specific to interact with various forms instructions and be input and output can reprogrammed as many times depending the microcontroller used [16]. Arduino uno performs a various function including data exchange between mobile and PLC. counting, calculate and monitor samples and provides necessary data string to the mobile application.

V. HARDWARE IMPLEMENTATION

The required equipment for complete hardware implementation of automatic packaging and monitoring system is shown in Fig. 4.

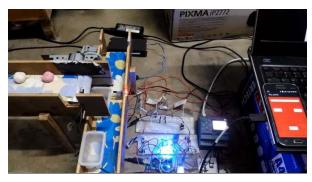


Fig. 4 Overall view of automatic packaging & monitoring system.

The major hardware equipment of the automatic packaging system are the following:

A. LOGO! 230 RCE PLC Module

LOGO! 230 **RCE** is a **PLC** module that is made for home appliances. It provides higher system stability and performance rather than a microprocessor. It comes with easy programming features i.e. ladder diagram that can programmed be using installation LOGO! the software Soft ACV8. The inputs (220V pulse) are provided by a four-array relay switch to the according to the command of arduino uno and the outputs (relay switch) that are connected with the conveyor motor circuits.

B. Arduino, Bluetooth Module and Android phone

Arduino uno is used to communicate phone **PLC** (LOGO! between mobile and 230 RCE) via bluetooth module. Moreover, directly sensors are connected generate respective logical arduino uno to **PLC** module. Data input of the strings provided arduino shown by uno are in Table IV.

TABLE IV
DATA STRING PROVIDED BY ARDUINO UNO

Operations in android	Data String		
phone and IR sensors	Data send by arduino	Data receives by arduino	
"Start" button	"Packaging Starts"	"a"	
"Stop" or "Exit" button	"Packaging Stops"	"Ъ"	
Box is sensed	"X box is sensed"		
Sample is sensed	"X sample is sensed"		

C. Conveyor Belts

Two conveyor belts made from are wood, dc motors with gearing, belts. proper **Belts** used and sensors. are for transporting samples from location one to

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which would be packaged into a specific plastic box later. Through the entire process, dc motor is used as actuators to move in conveyor belts. Proper gearing included for high torque with structure is Two IR (infrared receiver) moderate speed. one for detection are used, box sensors another for sample detection. Detection timing IR sensors is modified by arduino programming. arduino sends necessary Even strings the mobile phone bluetooth module for every detection of box sample. conveyor The belt system making procedure is shown in Fig. 5.







Fig. 5 Making procedure of conveyor belt.

COST ANALYSIS

An approximate analysis of the cost of equipment used in the proposed design and existed automation is represented in this section. DC motor, conveyor belt are the common equipment in both proposed automation and existed automation. Therefore, their cost is not considered in the analysis.

COST COMPARISON

Proposed Automat	ion	Existed Automation	
Equipment	Cost (USD)	Equipment	Cost (USD)
PLC (LOGO! 230 RCE)	243	PLC (LOGO! 230 RCE)	243
Arduino Uno	24	SIEMENS HMI	700
Bluetooth Module	9	Network Module/ Communication System (TCP/IP, Internet, GSM)	800*
Mobile with Android OS	70	Computer	300
IR sensors	10	CAM/ Sensors	50*
Total	356	Total	2093

^{*}Approximate cost of Network Module and CAM

VII. CONCLUSION

An automated packaging process with remote control and monitoring capability has been implemented. The main purpose of this design implementation is the reduction in the cost of automation. For lower capital industry or small industries, large automation high-configured devices economical. A reduction of almost 1700 USD become possible using the proposed design. The proposed design provides lowcost HMI to interact with the machine from remote places using the mobile. A warning or alert system and conveying path have been monitoring developed that and control plant can be done from a distant place from the plant. This ensures the reliability errorless process of the plant. proposed design has successfully tested using numerous trial and get a satisfactory result greater performance of reliability, with robustness, and less-error in packaging. design is feasible for low-capital industries as well as can be implemented for large industries.

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